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 CHAPTER 1 1.1 You are given the following differential equation with the initial condition, $v(t = 0) = 0$, $v_2 m c g$
 dt The numerical solution can be implemented as (0) 2 19.62

Chapra Applied Numerical Methods with MATLAB for Engineers and Scientists, 3 rd Ed. Errata: November 3,
 2011 Solution equation should add subscript lower case italic *i* to the *c* as shown Chapra Author: Dr. Steven
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Chapra—Canale: Numerical Methods for Engineers, Sixth Edition Ill. Linear Algebraic Equations 11. Special
 Matrices and Gauss—Seide The McGraw-Hil Companies, 2010 305 11.2 GAUSS-SEIDEL That is, the diagonal
 coefficient in each of the equations must be larger than the sum of the absolute values of the other coefficients in
 the equation.

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$(X_i' Y(X_i))$ on the solution curve. Note that the numerical solution is only a set of points, and nothing is said about
 values between the points. In the remainder of this chapter we describe various methods for obtaining a numerical
 solution $[(X_i' U_i)]$ -O' EXPLICIT METHODS We again consider (1.7) as the model differential equation and begin
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